# Transverse observables and the kinematic boundary 

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## Outline

- $m_{T(2)}$, kinks \&c.
- What does it all mean? The kinematic boundary
- Generalizations: combinatorics, non-identical decays, and the inverse of $m_{T(2)}$


## In the beginning ...

## The transverse mass

$m_{0}^{2}=m_{v}^{2}+m_{i}^{2}+2\left(E_{v} E_{i}-\mathbf{p}_{v} \cdot \mathbf{p}_{i}-q_{v} q_{i}\right)$

- $(E, \mathbf{p}, q)$ is 4-momentum

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## Transverse Mass $m_{T}$

$W \rightarrow I v$

CDF: $m_{W}=80.413 \pm 0.048 \mathrm{GeV}$
arXiv:0708.3642



## Identical Pair Decays and $m_{T 2}$

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mT(2) &c
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The boundary
Generalizations
Conclusions

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Lester \& Summers, PLB 463 99,1999
Barr et al., J.Phys.G29:2343-2363,2003
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## Pair Decays and $m_{T}{ }^{2}$

$t \bar{t} \rightarrow 2 b 2 W \rightarrow 2 b 2 / 2 v$

Cho et al. 0804.2185
Conclusions

CDF $m_{T 2}$ only: $m_{t}=167.9_{-5.0}^{+5.6} \mathrm{GeV}$
CDF note 9769



## $m_{T(2)}$ and the kink

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- $m_{T}$ is unobservable if $m_{i}$ unknown
- Consider $m_{T}=m_{T}\left(m_{i}\right)$
- Lose boundedness but gain a kink

Choi et al., 0709.0288<br>BMG, JHEP 02080512008<br>Barr, BMG \& Lester, JHEP 0208 014, 2008<br>Choi et al., 0711.4526

## $m_{T(2)}$ and the kink

Pair Three-body decay $2 \tilde{g} \rightarrow 2 q 2 \bar{q} 2 \tilde{\chi}_{1}^{0}$

Barr, BMG \& Lester, JHEP 0208 014,2008


$m_{T(2)}$ \& c
The boundary

What does all of this mean?

## What does all of this mean?

- ad hoc definition of $m_{T(2)}$
- ad hoc generalization to hypothesized masses
- In fact these are natural objects ...

The Kinematic Boundary

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## Kinematic constraints for an event:

Unknowns are $p_{i}$ and ( $m_{i}, m_{0}$ )

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Theorem: a solution exists for $m_{0} \geq m_{T}\left(m_{i}\right)$

Proof: Two parts

- Part 1: Prove any solution has $m_{0} \geq m_{T}\left(m_{i}\right)$
- Part 2: Prove that there is a solution with $m_{0}=m_{T}\left(m_{i}\right)$


## Part 1

Prove any solution has $m_{0} \geq m_{T}\left(m_{i}\right)$

- $m_{0}^{2}=m_{i}^{2}+m_{v}^{2}+2\left(E_{i} E_{v}-\mathbf{p}_{i} \cdot \mathbf{p}_{v}-q_{i} q_{v}\right)$
- $m_{T}^{2} \equiv m_{i}^{2}+m_{v}^{2}+2\left(e_{i} e_{v}-\mathbf{p}_{i} \cdot \mathbf{p}_{v}\right)$
- $E_{i} E_{v}-q_{i} q_{v} \geq e_{i} e_{v}$, equality at $E_{i} q_{v}-E_{v} q_{i}=0$ $\Longrightarrow m_{0} \geq m_{T}\left(m_{i}\right)$

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- $\Longrightarrow m_{0} \geq m_{T}\left(m_{i}\right)$


## Part 2

## Prove $m_{0}=m_{T}\left(m_{i}\right)$ has a solution

- Find suitable $E_{i}, q_{i}$
- Need $\frac{q_{i}}{q_{i}^{2}+e_{1}^{2}}=\frac{q_{v}}{E_{v}} \in[-1,+1]$


## Proof for $m_{T 2}$ not much harder

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## The kinematic boundary

New definition of $m_{T(2)}$ as "the kinematic boundary of an event"

## So what?

- Faster algorithm for computing $m_{T 2}$
- $m_{T(2)}$ is the best one can do without extra kinematics or dynamics
- Easier proofs of kinks \&c.
- Generalize


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Cheng and Han, arXiv:0810.5178

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Generalizations

## Generalizations I: Combinatorics

Combinatoric ambiguities

- Branch assignments
- Initial State Radiation
-What is the kinematic boundary?
- Union of allowed regions


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Alwall et al, arXiv:0905.1201

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## Generalizations II: Non-identical decays

Always considered identical pair decays.
But parents/daughters need not be the same

Distinct parents:

- Squark-aluino production in MSSM

Distinct daughters

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$>$ few m
e.g. Neutrini, Multiple photini


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## Generalizations II: Non-identical decays

$m_{T 2}$ is not much good...

... use the kinematic boundary?

## Generalizations II: Non-identical decays

Focus on case with non-identical parents

- 3-d space of unknown masses $\left(m_{i}, m_{0}, m_{0}^{\prime}\right)$
- Kinematic boundary is a surface

Extremal surface from decoupling argument

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Constraints
The boundary
Generalizations
Conclusions

- $\left(p_{i}+p_{v}\right)^{2}=m_{0}^{2}$
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## Ditto for the other decay, plus

## Last equation decouples for extremal surface

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## Generalizations II: Non-identical decays

## Extremal surface

$m_{T(2)}$ \& C
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Lots of interesting kinks ...

## Generalizations II: Non-identical decays

Is there an analogue of the usual $m_{T 2}$ ?
$m_{T 2}^{2}\left(m_{i}, m_{i}^{\prime}, \frac{m_{0}}{m_{0}^{\prime}}\right)=\min \max \left(\frac{m_{0}^{\prime}}{m_{0}} m_{T}^{2}, \frac{m_{0}}{m_{0}^{\prime}} m_{T}^{\prime 2}\right)$

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## Generalizations III: The inverse of $m_{T(2)}$

Use $m_{0}=m_{T(2)}\left(m_{i}\right)$ if you know the mass of the daughter but not the parent...
what about the other way round?

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- Need the inverse of $m_{0}=m_{T(2)}\left(m_{i}\right)$


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## Generalizations III: The inverse of $m_{T(2)}$

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- $m_{T 2}=\min \max \left(m_{T}, m_{T}^{\prime}\right)$
- $m_{T 2}^{-1}=\max \min \left(m_{T}^{-1}, m_{T}^{\prime-1}\right)$


## Conclusions

- $m_{T(2)} \& c$ are natural objects: define kinematic boundary
- Also the "best" objects
- Easily generalized

